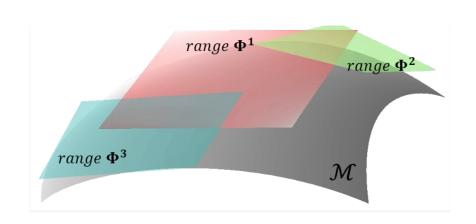


Barcelona 7<sup>th</sup>-9<sup>th</sup> September 2021



# Clustering Techniques for Enhanced Reduced Order Model Simulations in Structural Mechanics



Mr. J Raul Bravo M

Prof. Riccardo Rossi

Prof. Joaquin Hernandez



### Presenting ourselves



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Kratos github site



### Outline of the talk

- Proper Orthogonal Decomposition POD
- Local POD
- Our proposals:
  - Overlapping
  - HROM with multiple bases
- Examples run in Kratos Multiphysics
- Conclusions



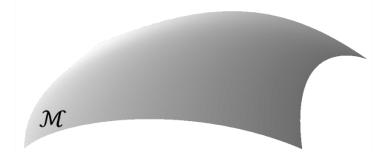
#### **Full Order Model (FOM)**

 $r(u;\mu)=0$ 

 $u \in \mathbb{R}^n$ : state vector

 $\mu \in \mathcal{P} \subset \mathbb{R}^p$ : parameters vector

Solution manifold:  $\mathcal{M} = \{ u(\mu) \mid \mu \in \mathcal{P} \} \subset \mathbb{R}^n$ 



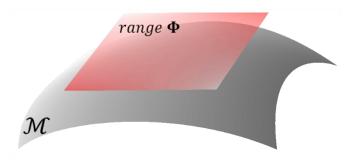
Let  $u \approx \Phi q$ 

#### Reduced Order Model (ROM)

 $\mathbf{\Phi}^T r(\mathbf{\Phi} \mathbf{q}; \boldsymbol{\mu}) = \mathbf{0}$ 

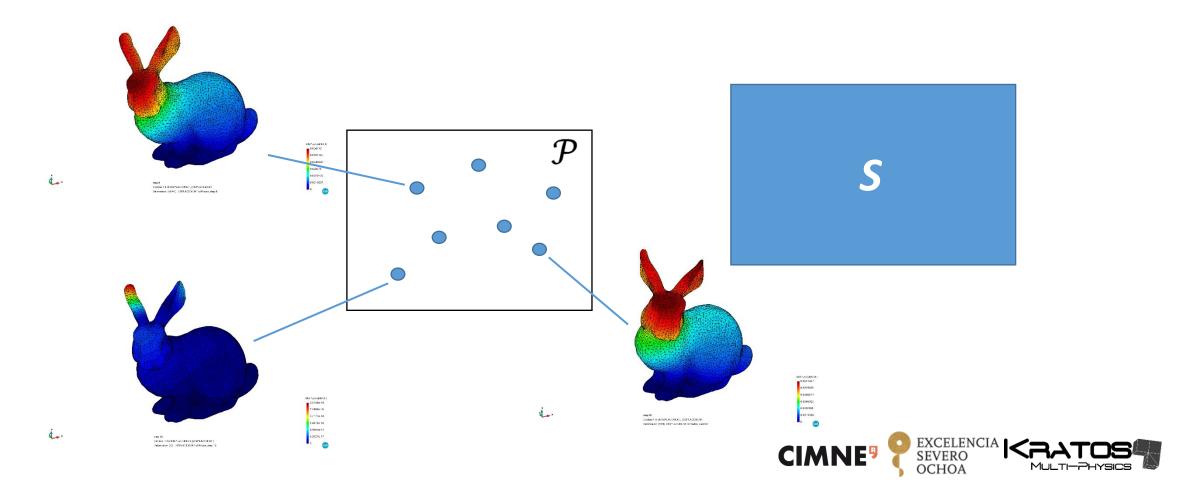
 $q \in \mathbb{R}^k$ : reduced state vector

A MUCH SMALLER SYSTEM!





Solve the FOM using Finite Elements to find  $u(\mu)$ 



• Take the SVD of  $S = U\Sigma V^{\mathrm{T}} pprox U_k \Sigma_{\mathrm{k}} V_{\mathrm{k}}^{\mathrm{T}}$ 

$$S$$
 =  $U$   $\Sigma$   $V^T$ 



• Take the SVD of  $S = U\Sigma V^{\mathrm{T}} \approx U_k \Sigma_{\mathrm{k}} V_{\mathrm{k}}^{\mathrm{T}}$ 







• Take the SVD of  $S = U\Sigma V^{\mathrm{T}} pprox U_k \Sigma_{\mathrm{k}} V_{\mathrm{k}}^{\mathrm{T}}$ 

$$\Phi \coloneqq U_k$$



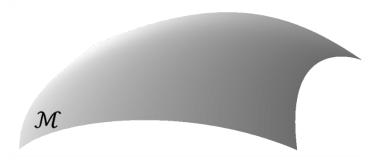
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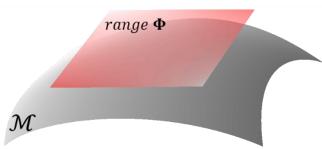
#### Reduced Order Model (ROM)

$$\Phi^T r \left( \Phi \mathbf{q} \right) \mu ) = 0$$

 $q \in \mathbb{R}^k$ : reduced state vector

A MUCH SMALLER SYSTEM!







## Hyper-reduction

The goal is to find a **subset of elements and corresponding weights** by solving an optimization problem

$$(E, W) = \arg\min \|\zeta\|_{0}$$
s.t. 
$$\|G\mathbf{1} - G\zeta\|_{2}^{2} \le \epsilon \|G\mathbf{1}\|_{2}^{2}$$

$$\zeta_{i} \ge 0$$

Where 
$$G = G(\Phi,R)$$
 parameters

#### NP-HARD. Solving via greedy procedure

$$(E, W) = \arg\min \left\| \sum_{i=1}^{n} g_{i} - \sum_{i \in E} g_{i} \omega_{i} \right\|_{2}^{2}$$

$$s. t. \quad \omega_{i} > 0$$

(Hernández, 2020): doi.org/10.1016/j.cma.2020.113192

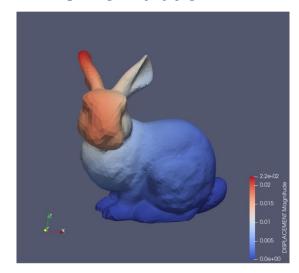


## Hyper-reduction

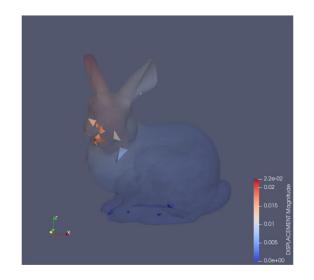
Assembly comparison FOM vs HROM:

$$\left(\prod_{e=1}^{n \text{ elem}} A_e\right) \boldsymbol{u} = \prod_{e=1}^{n \text{ elem}} b_e \qquad \qquad \left(\sum_{e \in E} \boldsymbol{\Phi}_e^T A_e \boldsymbol{\Phi}_e \, \boldsymbol{\omega}_e\right) \boldsymbol{q} = \sum_{e \in E} \boldsymbol{\Phi}_e^T \, \boldsymbol{b}_e \, \boldsymbol{\omega}_e$$

#### **FOM Simulation**



#### **HROM Simulation**

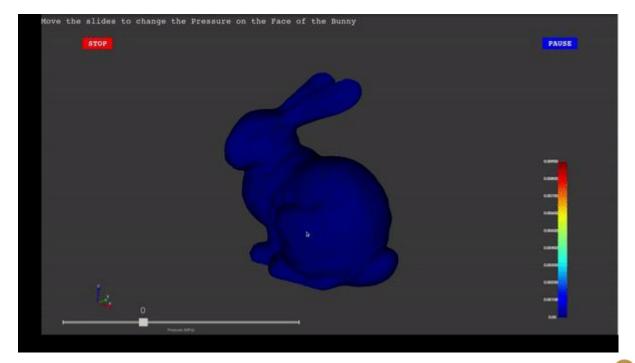




## Hyper-reduction

$$\left(\sum_{e \in E} \mathbf{\Phi}_e^T A_e \mathbf{\Phi}_e \omega_e\right) q = \sum_{e \in E} \mathbf{\Phi}_e^T b_e \omega_e$$

#### **HROM Simulation**





### POD weaknesses and strengths

Straightforward procedure for training and inference

 Not ideal for certain problems(convection dominated, highly nonlinear)



### Local POD

#### **Full Order Model (FOM)**

 $r(u;\mu)=0$ 

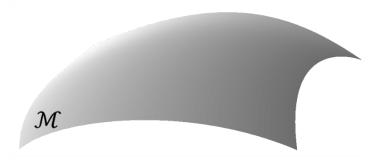
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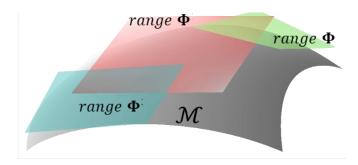
#### **Reduced Order Model (ROM)**

$$\Phi^{1} r(\Phi^{1} q; \mu) = 0$$
  
 $q \in \mathbb{R}^{k^{1}}$ : reduced state vector

Solution manifold:  $\mathcal{M} = \{ u(\mu) \mid \mu \in \mathcal{P} \} \subset \mathbb{R}^n$ 



Let  $u \approx \Phi^i q$ 





### Local POD

#### **Full Order Model (FOM)**

 $r(u;\mu)=0$ 

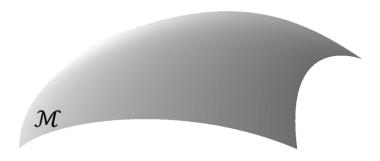
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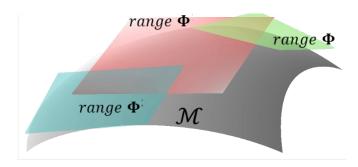
#### **Reduced Order Model (ROM)**

$$\Phi^2 r(\Phi^2 \mathbf{q}; \mu) = \mathbf{0}$$
  
 $\mathbf{q} \in \mathbb{R}^{k^2}$ : reduced state vector

Solution manifold:  $\mathcal{M} = \{ u(\mu) \mid \mu \in \mathcal{P} \} \subset \mathbb{R}^n$ 



Let  $u \approx \Phi^i q$ 





### Local POD

#### **Full Order Model (FOM)**

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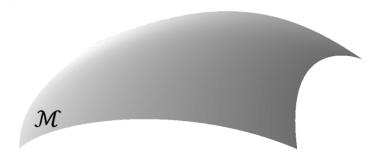
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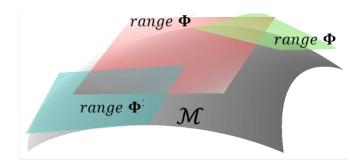
#### **Reduced Order Model (ROM)**

$$\Phi^{3} r(\Phi^3 q; \mu) = 0$$
  
 $q \in \mathbb{R}^{k^3}$ : reduced state vector

Solution manifold:  $\mathcal{M} = \{ u(\mu) \mid \mu \in \mathcal{P} \} \subset \mathbb{R}^n$ 



Let  $u \approx \Phi^i q$ 





### Local POD. K-means

Given:  $\{u_j\}_{j=1}^m$ 

Find centroids:  $\{c_i\}_{i=1}^k$  and assignments:  $s_{ij}$ 

$$\min \sum_{j=1}^{k} \sum_{i}^{m} s_{ij} \| \boldsymbol{u}_{j} - \boldsymbol{c}_{i} \|_{2}^{2}$$

$$s. t. \sum_{i}^{k} s_{ij} = 1, \quad s_{ij} \in \{0,1\}$$

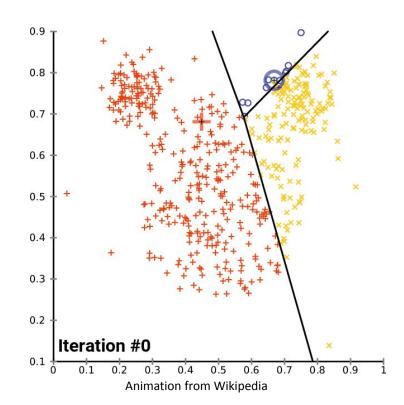
$$s.t.\sum_{i} s_{ij} = 1$$
,  $s_{ij} \in \{0,1\}$ 



#### Solve via alternating minimization:

$$s_{ij} = \begin{cases} 1 & nearest centroid \\ 0 & otherwise \end{cases}$$

$$c_i = \frac{\sum_{j=1}^m s_{ij} \boldsymbol{u}_j}{\sum_{j=1}^m s_{ij}}$$



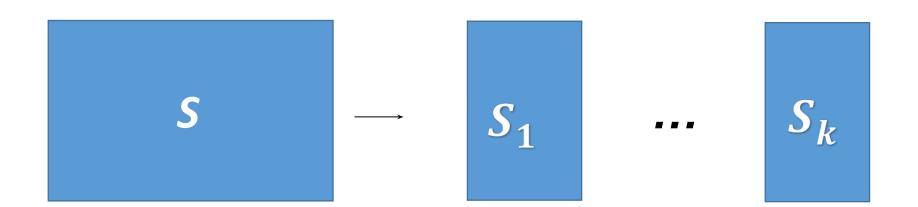




### Local POD. Building multiple bases

Use an unsupervised learning method to build clusters

**1.** Get Non-overlapping clusters  $S_i = kmeans(S)$ 



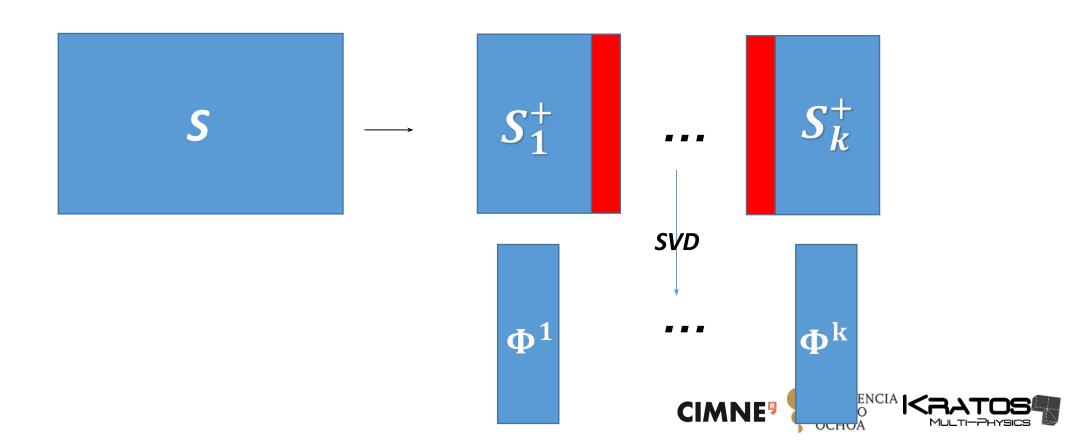


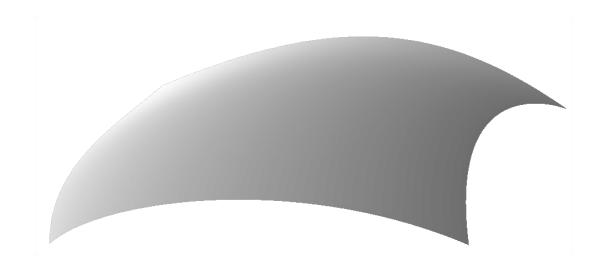
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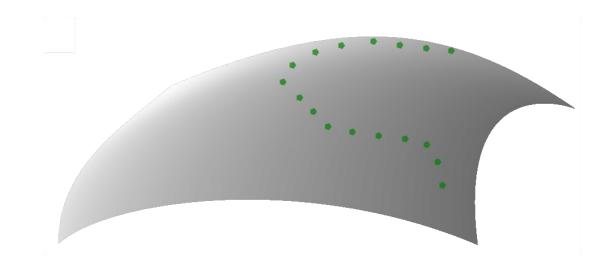
**1.** Get Non-overlapping clusters  $S_i = kmeans(S)$ 

2. Add some overlapping  $S_i^+ = overlap(S_i)$ 

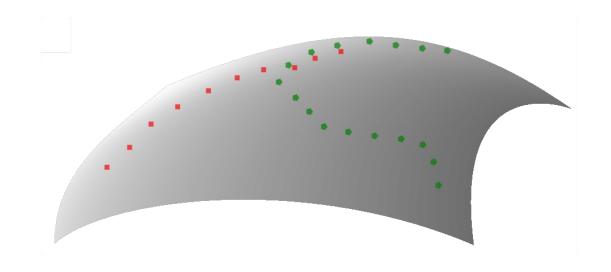




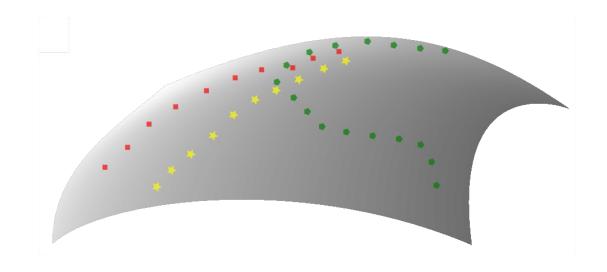




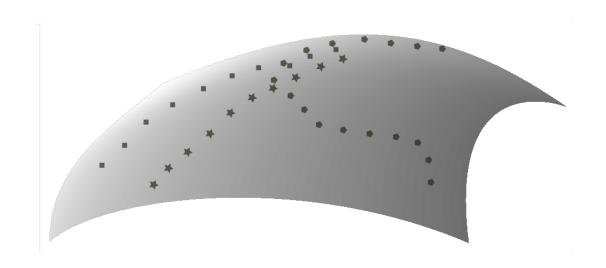




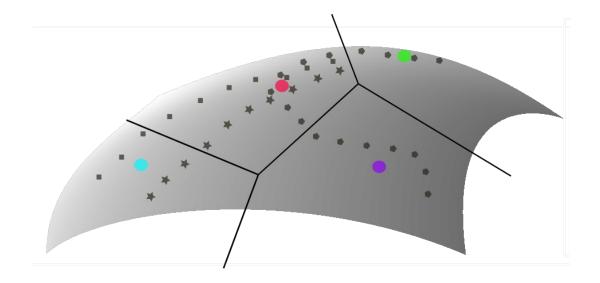




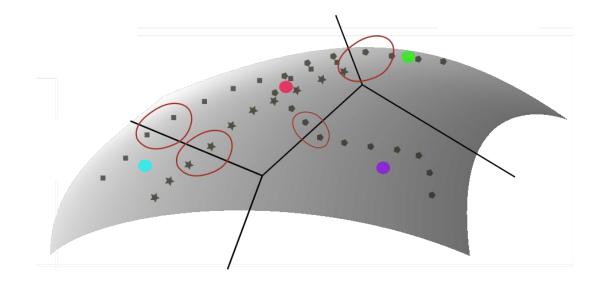




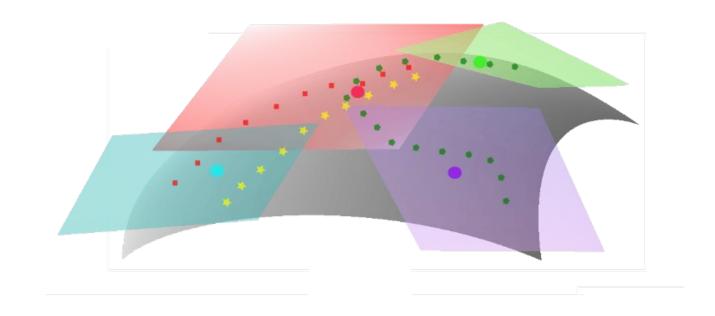




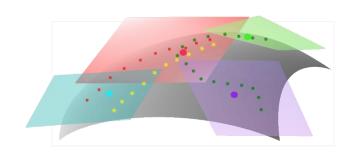




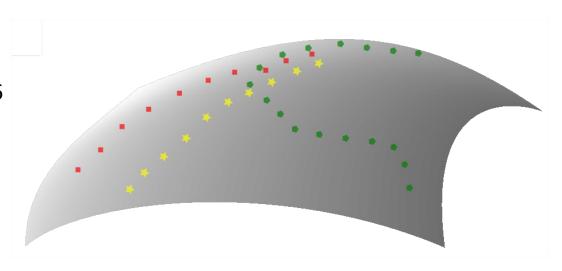






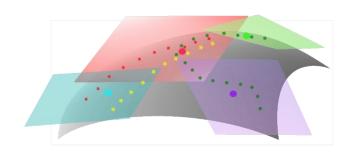


(Farhat, 2012): doi.org/10.2514/6.2012-2686

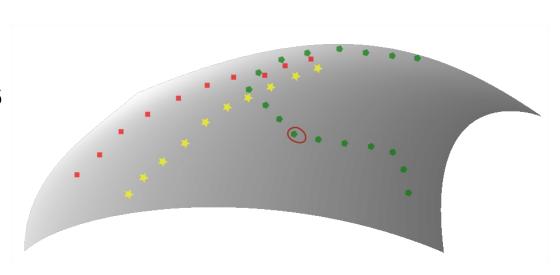


Our overlapping proposal



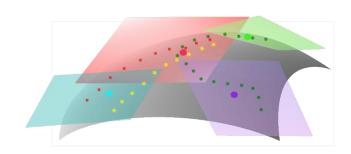


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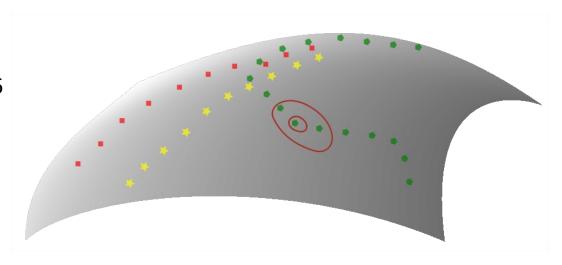
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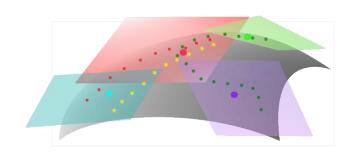
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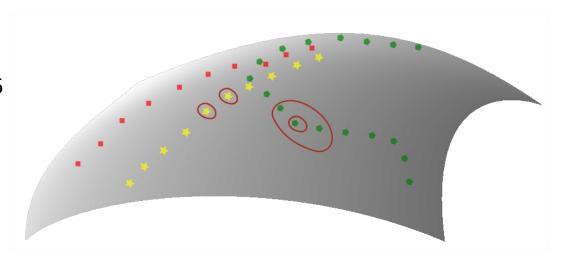
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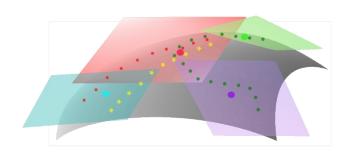
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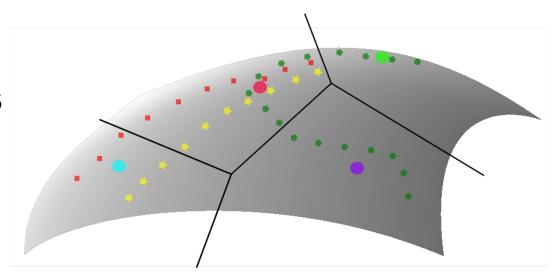


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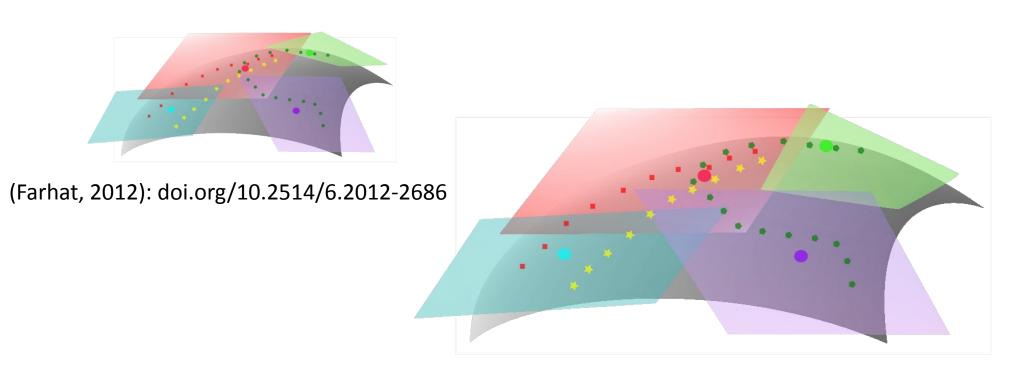


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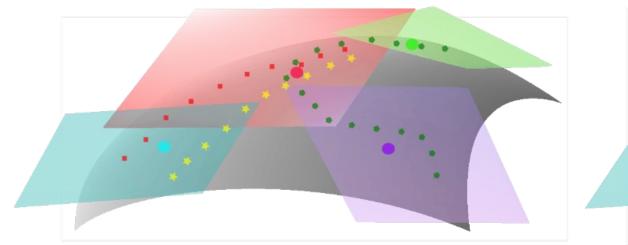
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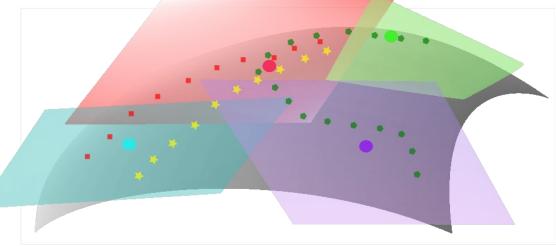


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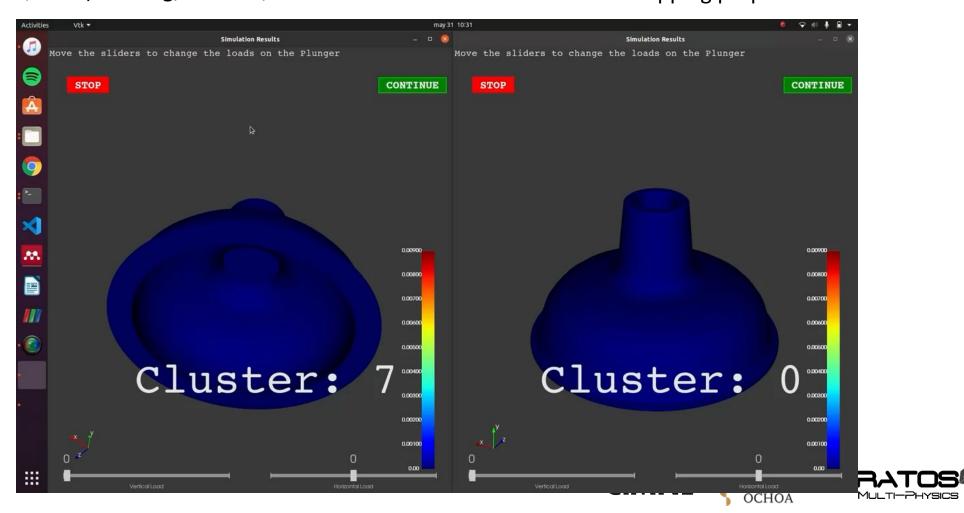
Our overlapping proposal



### Local POD. Example 1

(Farhat, 2012): doi.org/10.2514/6.2012-2686

Our overlapping proposal



#### Locally Linear Embedding LLE:

$$\min_{c} \sum_{j=1}^{N} \| \mathbf{x}_{j} - \sum_{i=1}^{N} c_{ij} \mathbf{x}_{i} \|_{2}^{2}$$

s.t. 
$$c_{ij} = 0$$
 if  $\mathbf{x}_i$  not  $k - NN$  to  $\mathbf{x}_j$ 

$$\sum_{i=1}^{N} c_{ij} = 1$$

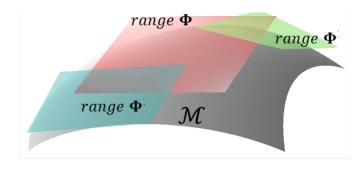
(Roweis, 2000): doi.org/10.1126/science.290.5500.2323

- 1. Get Non-overlapping clusters  $S_i = kmeans(S)$
- 2. Add necessary overlapping  $S_i^+ = overlap(S_i)$

Each cluster  $S_i^+$  should consist on its snapshots, and the neighbours of its snapshots



$$\mathbf{\Phi}^{\mathbf{3}^T} r(\mathbf{\Phi}^{\mathbf{3}} \mathbf{q}; \boldsymbol{\mu}) = \mathbf{0}$$

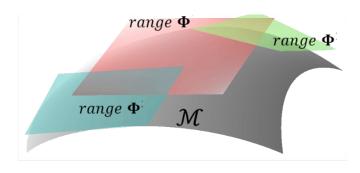


$$G = G(\Phi, R)$$





$$\mathbf{\Phi^1}^T r(\mathbf{\Phi^1}\mathbf{q}; \boldsymbol{\mu}) = \mathbf{0}$$

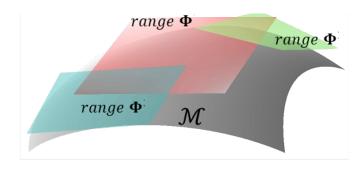


$$G = G(\Phi, R)$$

$$oldsymbol{G_3}{G_1}$$



$$\Phi^2 r(\Phi^2 \mathbf{q}; \mu) = \mathbf{0}$$



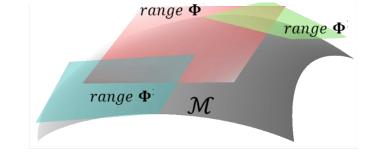
$$G = G(\Phi, R)$$

$$egin{array}{c} G_3 \ G_1 \ G_2 \end{array}$$



#### **Reduced Order Model (ROM)**

$$\Phi^2 r(\Phi^2 \mathbf{q}; \mu) = \mathbf{0}$$



$$G = G(\Phi, R)$$

$$(E, W) = \operatorname{arg\,min} \left\| \sum_{i=1}^{n} g_{i} - \sum_{i \in E} g_{i} \omega_{i} \right\|_{2}^{2}$$

$$s.t. \quad \omega_{i} > 0$$

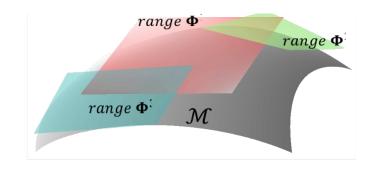
(Grimberg, 2020): doi.org/10.1002/nme.6603





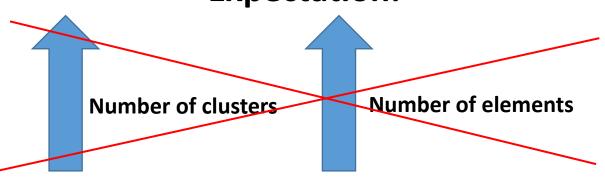
#### **Reduced Order Model (ROM)**

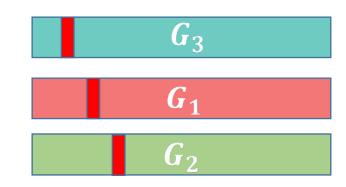
$$\Phi^2 r(\Phi^2 \mathbf{q}; \mu) = \mathbf{0}$$



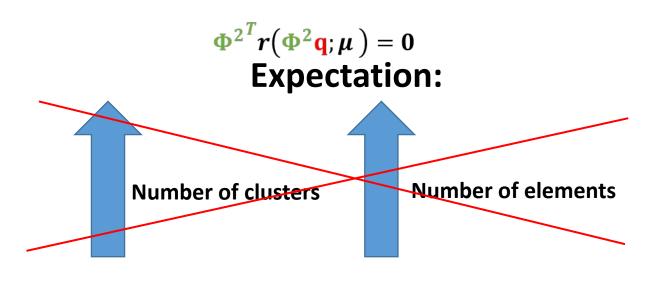
$$G = G(\Phi, R)$$

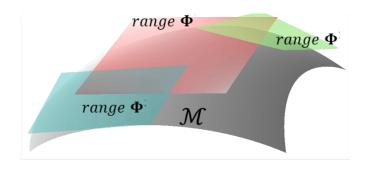
#### **Expectation:**



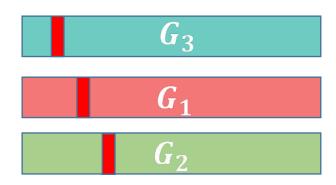






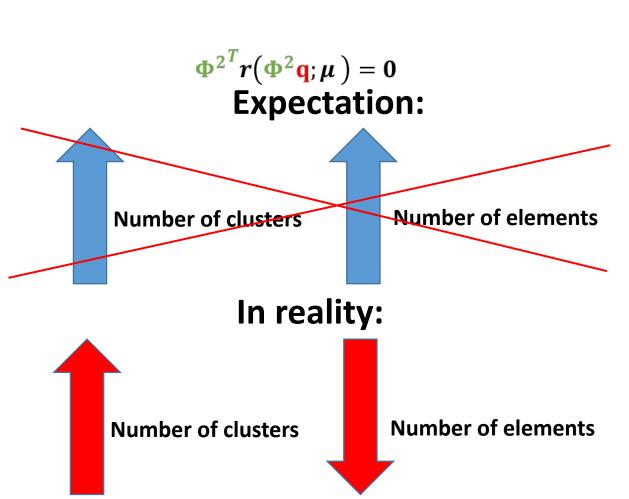


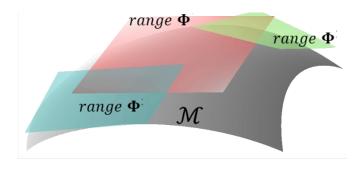
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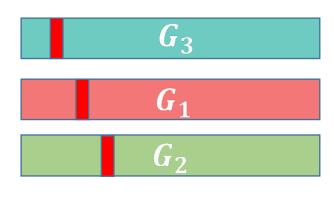








$$G = G(\Phi, R)$$





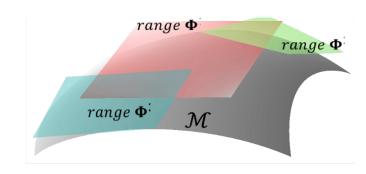
#### **Reduced Order Model (ROM)**

$$\Phi^2 r(\Phi^2 \mathbf{q}; \mu) = \mathbf{0}$$

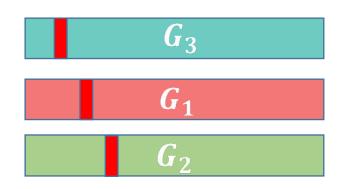
$$(E,\widehat{W}) = \operatorname{arg\,min} \left\| \sum_{i=1}^{n} g_{i}^{k} - \sum_{i \in E} g_{i}^{k} \widehat{\omega}_{i} \right\|_{2}^{2}$$

s.t. 
$$\widehat{\omega}_i \geq 0$$

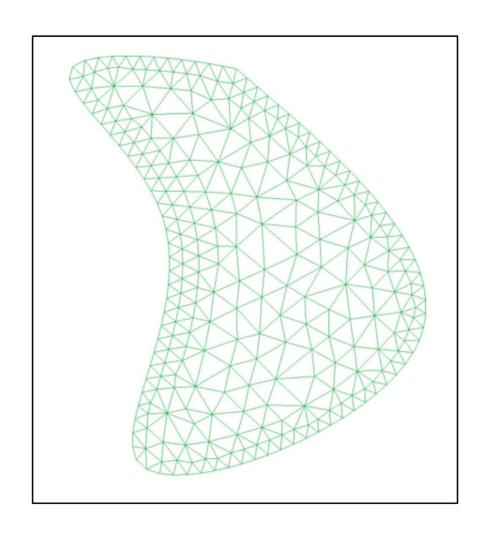
Find a single set of elements and as many sets of weights as bases



$$G = G(\Phi, R)$$



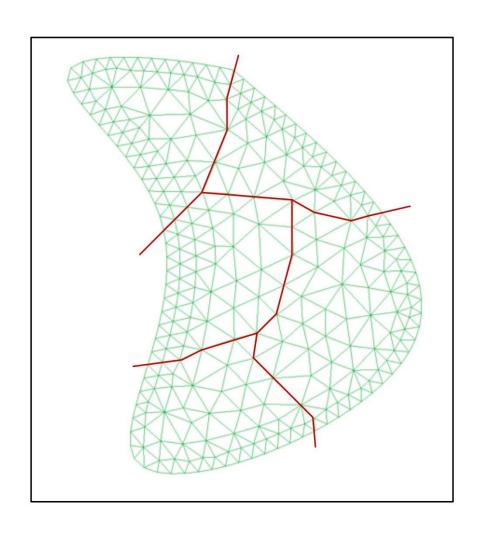


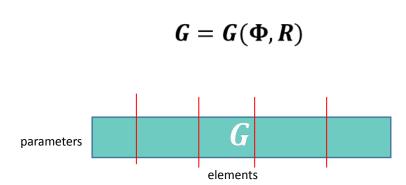


$$G = G(\Phi, R)$$

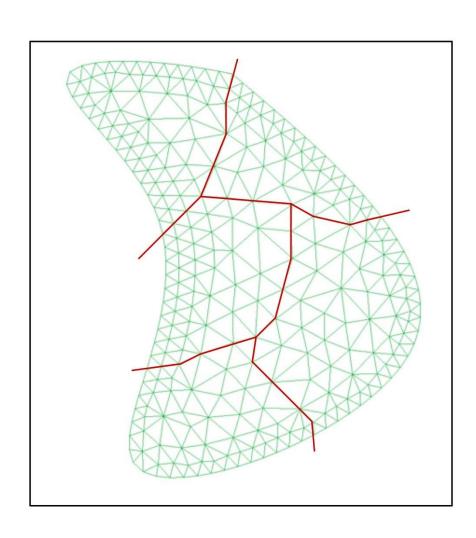
parameters **G** 





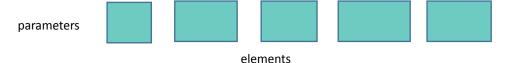




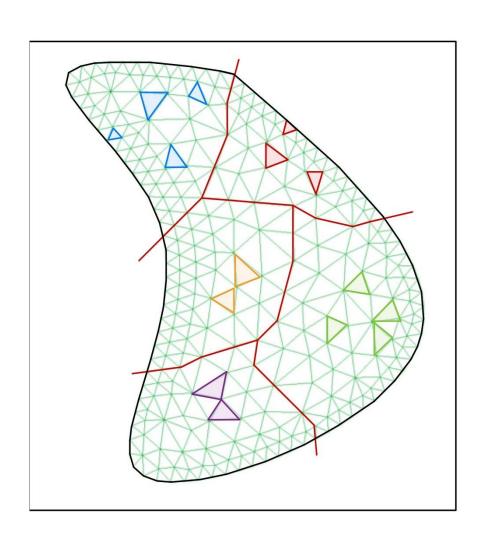


$$(E, W) = ECM(G)$$

$$G = G(\Phi, R)$$

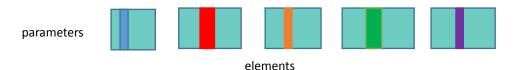




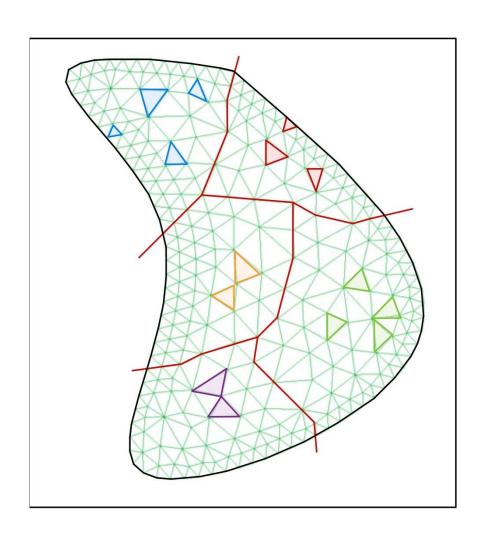


$$(E, W) = ECM(G)$$

$$G = G(\Phi, R)$$







$$(E, W) = ECM(G)$$

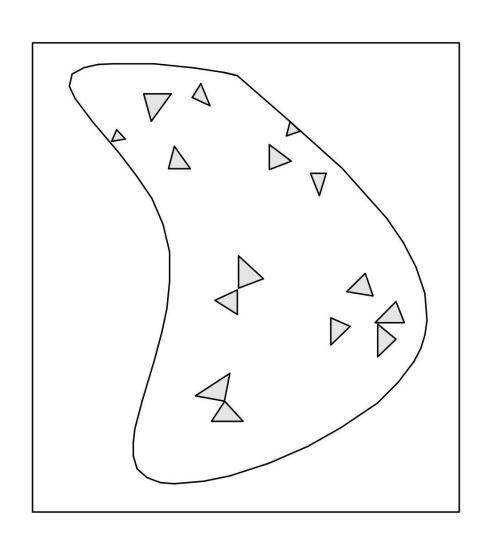
$$G = G(\Phi, R)$$

parameters



elements





$$(E, W) = ECM(G)$$

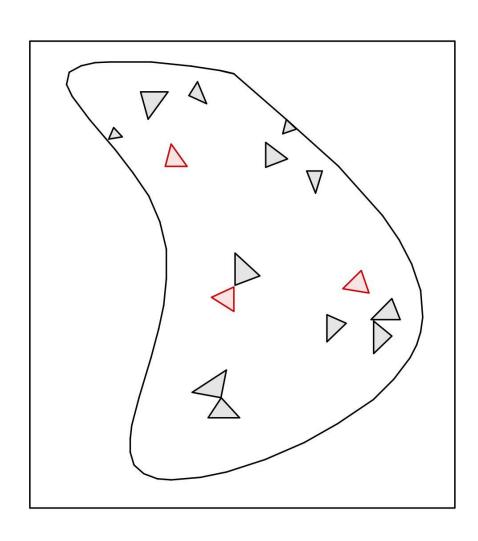
$$G = G(\Phi, R)$$

parameters



elements





$$(E, W) = ECM(G)$$

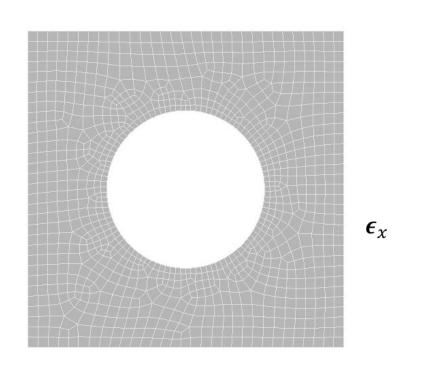
$$G = G(\Phi, R)$$

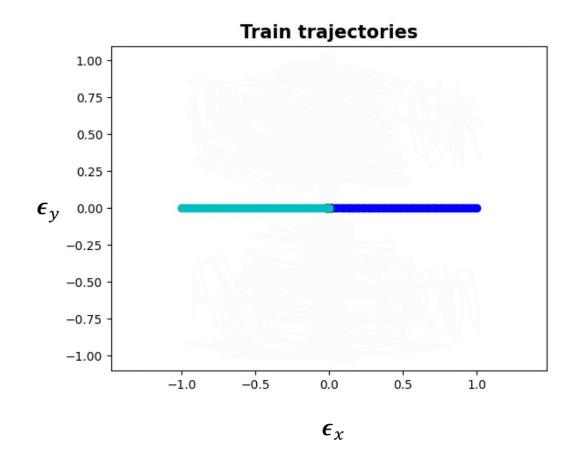
parameters



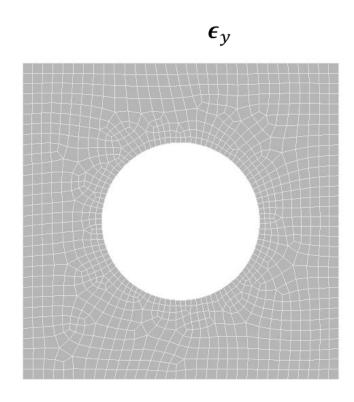
elements

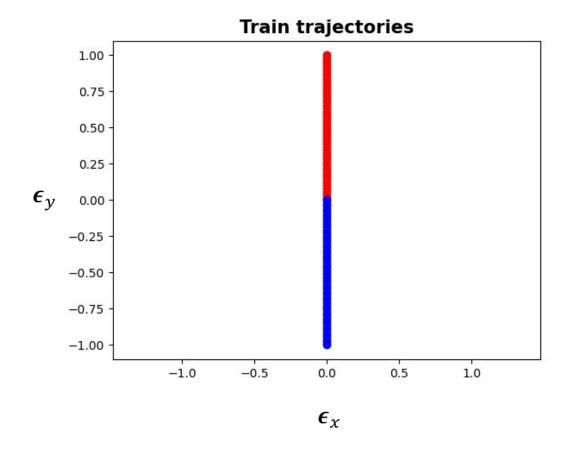




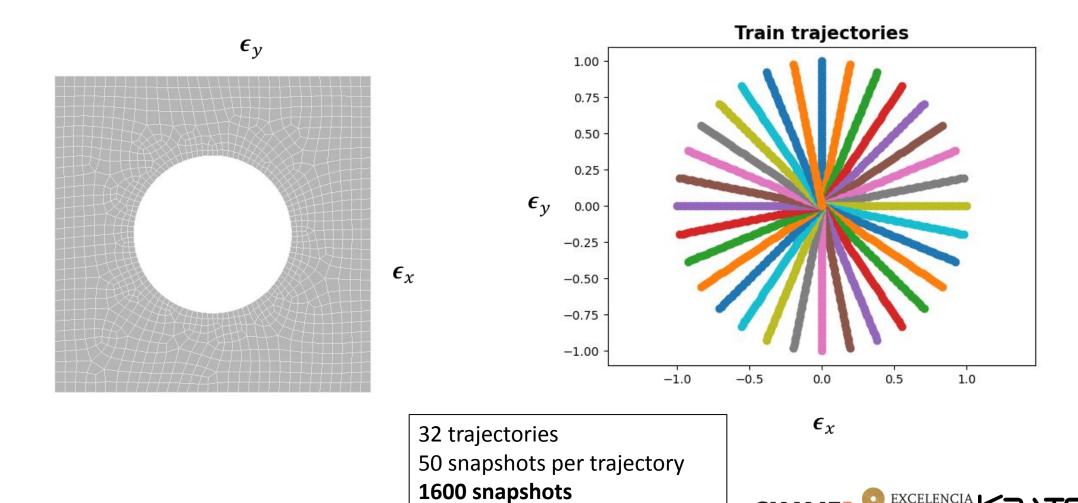


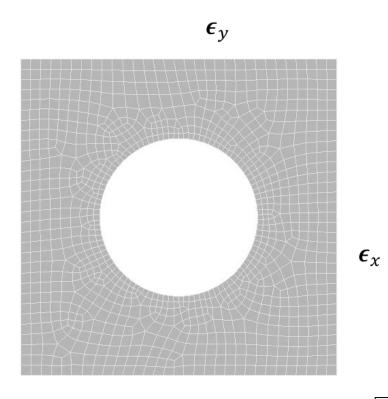


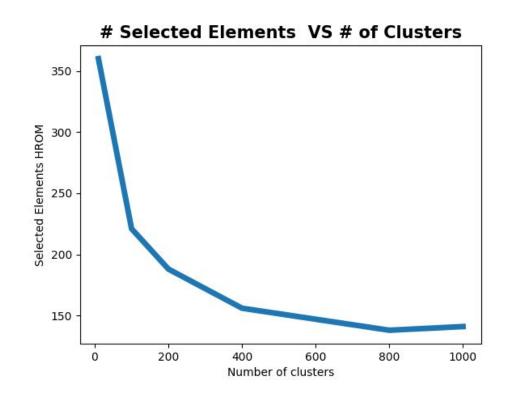






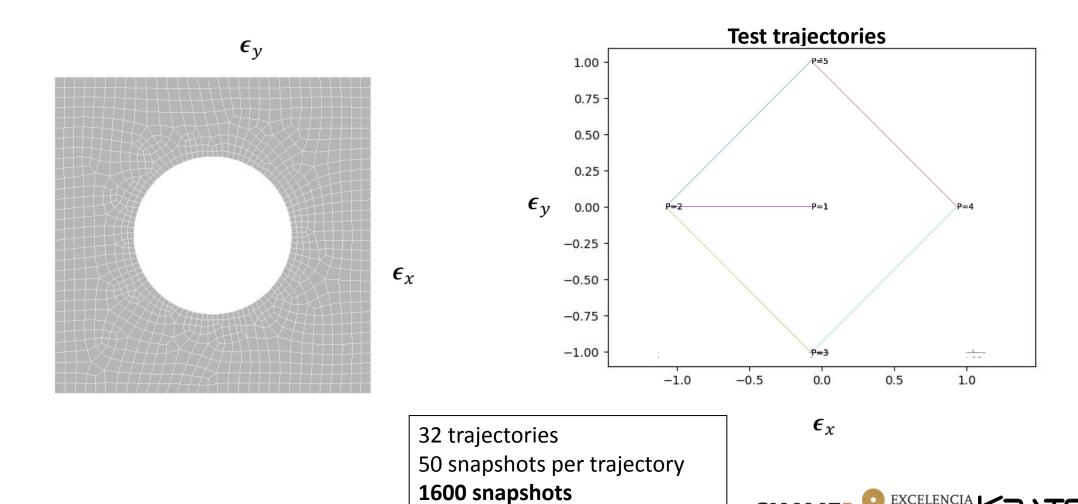






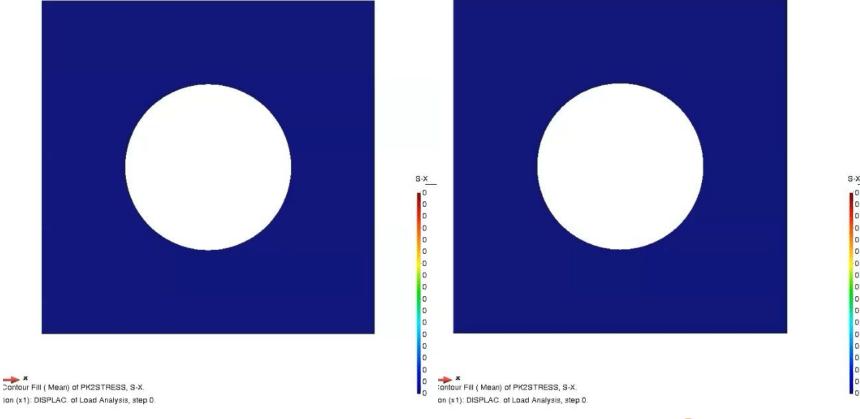
32 trajectories50 snapshots per trajectory1600 snapshots





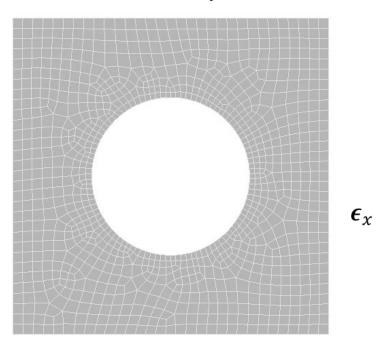
# Local POD. Example 2 FOM

#### **HROM**





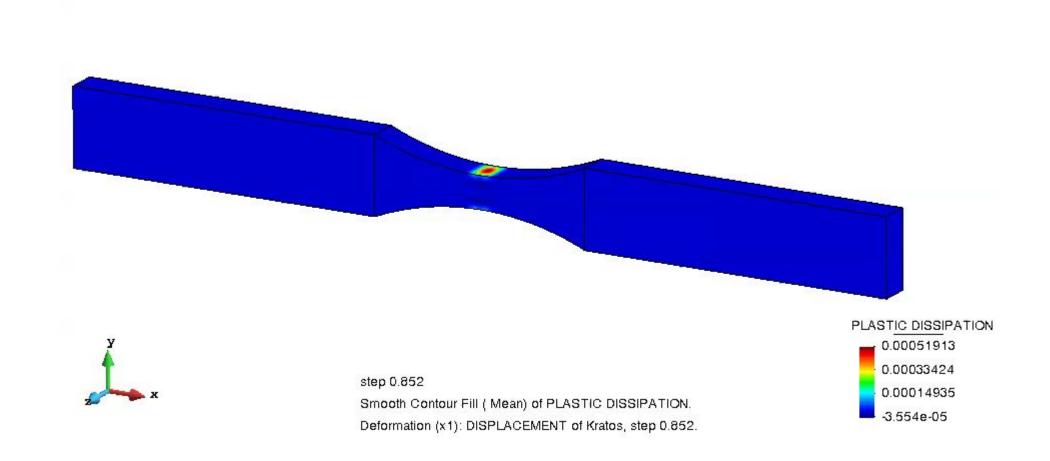




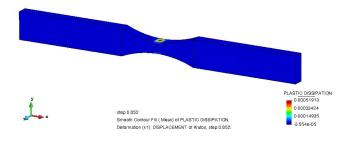
**10X** less elements required compared with a single basis

**5X** less modes required compared with a single basis









	POD	Local POD
Basis size	260 modes	10 basis ~30 modes
HROM elements	400	240(~150 per basis)
Simulation time	1234 seg	90 seg
L2 error	1e-3%	1e-3%

**13X** faster than POD



## Local POD. Strengths and weaknesses

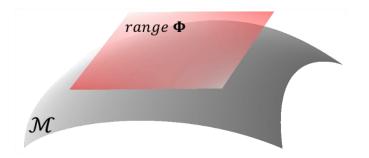
- Reasonable overhead in training and negligible in inference
- Smaller bases and elements sets, therefore faster ROMs

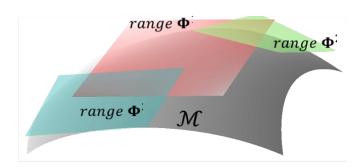
Easy to overfit to training trajectories



#### General conclusions

- The Local POD was presented
  - Advantages using our robust overlapping and hyper-reduction
- Future work:
  - application of method to multiple escenarios
  - combination of Local POD with DL







#### THANK YOU

#### **GRATEFUL TO:**





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Link to Kratos github site



#### References:

- [1] Hernández, J. A. (2020). A multiscale method for periodic structures using domain decomposition and ECM-hyperreduction. *Computer Methods in Applied Mechanics and Engineering*, 368, 113192.
- [2] Washabaugh, K., Amsallem, D., Zahr, M., & Farhat, C. (2012, June). Nonlinear model reduction for CFD problems using local reduced-order bases. In *42nd AIAA Fluid Dynamics Conference and Exhibit* (p. 2686).
- [3] Roweis, S. T., & Saul, L. K. (2000). Nonlinear dimensionality reduction by locally linear embedding. *science*, *290*(5500), 2323-2326.
- [4] Grimberg, S., Farhat, C., Tezaur, R., & Bou-Mosleh, C. (2021). Mesh sampling and weighting for the hyperreduction of nonlinear Petrov–Galerkin reduced-order models with local reduced-order bases. *International Journal for Numerical Methods in Engineering*, 122(7), 1846-1874.

